

BeaulieuJM.ca/publi/Bea2017a

**MEAN-SHIFT POLSAR IMAGE DENOISING
WITH POSITION TENSOR**

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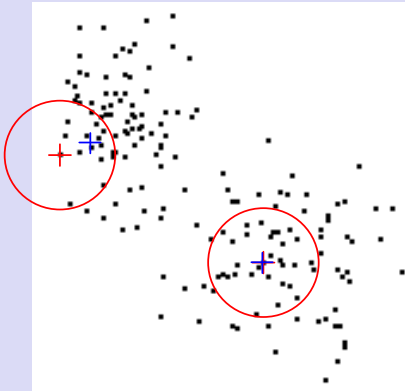


MEAN-SHIFT POLSAR IMAGE DENOISING WITH POSITION TENSOR

- MeanShift Clustering
- Distance measures for PolSAR images
- Tensor spatial attribute

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- **Mean-Shift clustering** move every data points toward higher probability density zones (modes)
- **Density** \rightarrow point count over a window (histogram)
- **Direction** toward higher density
 \rightarrow position of weighted mean (window)



MEAN-SHIFT

Radiometric

$$D_{rad} = D(Z_i, Z_j)^{1/2} / F_{rad}$$

Distance

$$D_{spatial} = \text{Distance between pixels} / F_{spatial}$$

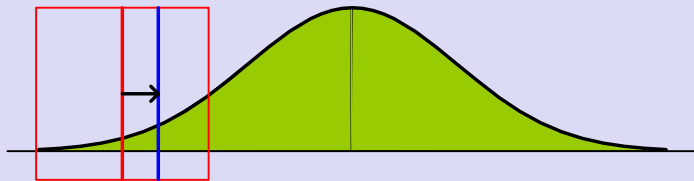
$$\text{Weight} = \text{EXP} [- (D_{rad}^2 + D_{spatial}^2)]$$

Mean = weighted pixel mean

$$F_{hift}_R = \alpha \text{ value}_R + (1-\alpha) \text{ Mean}_R \quad (\text{radiometric value})$$

New

Old



- Radiometric distance $D(Z_i, Z_j)$ for PolSar images
- Z_k is pixel covariance matrix
- Non textured PolSar image
- Z_k follows a complex Wishart distribution

$$p(Z_k | \Sigma) = \frac{L^{3L} |Z_k|^{L-3} \exp\{-L \operatorname{tr}(\Sigma^{-1} Z_k)\}}{\pi^3 \Gamma(L) \Gamma(L-1) \Gamma(L-2) |\Sigma|^L}$$

- Log of the likelihood ratio statistic is

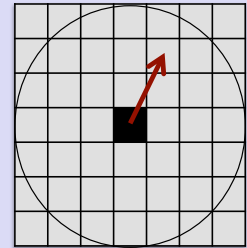
$$D(Z_i, Z_j) = 2 \ln \left| \frac{1}{2} (Z_i + Z_j) \right| - \ln |Z_i| - \ln |Z_j|$$

- Distance between pixels → Euclidian distance

Gaussian like weight ($F_{spatial} = \sigma$)

Weight = EXP [- ($D_{rad}^2 + D_{spatial}^2$)]

Limited to a window (11x11)



$$\text{Shift}_R = \alpha \text{ value}_R + (1-\alpha) \text{ Mean}_R$$

New ↑ Old ↑ Radiometric ↑

- Shifting the pixel position

$$F_{shift}_p = \alpha \text{ value}_p + (1-\alpha) \text{ Mean}_p \quad \text{Position} \quad \text{(pixel position)}$$

Distances between pixels will change

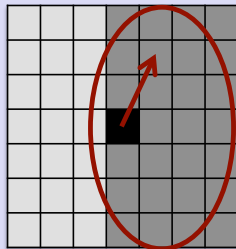
- **Integrating other distances (texture, shape)**
- **Using weight to define a new attribute**

$p_i = (x_i, y_i) \rightarrow$ pixel position

$V_i =$ position covariance or tensor

$$V_i = \sum_j w_{i,j} (p_j - p_i) (p_j - p_i)^t$$

i \rightarrow center
j \rightarrow neighbour



Use V_i ellipse shape (orientation, elongation)

Shape indicate edge orientation

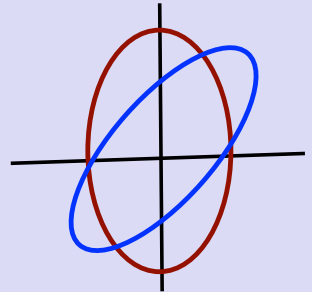
- **Using V_i in weight calculation**

Use S1 measure of Garcia to calculate the difference between V_i and V_j

(BMC Evolutionary Biology 2012, 12:222)

$$D_V = S1(V_i, V_j)^{1/2} / F_V$$

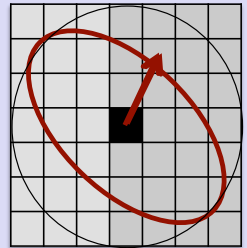
$$\text{Weight} = \text{EXP} [-(D_{rad}^2 + D_{spa}^2 + D_V^2)]$$



- **Shifting the value of V_i**

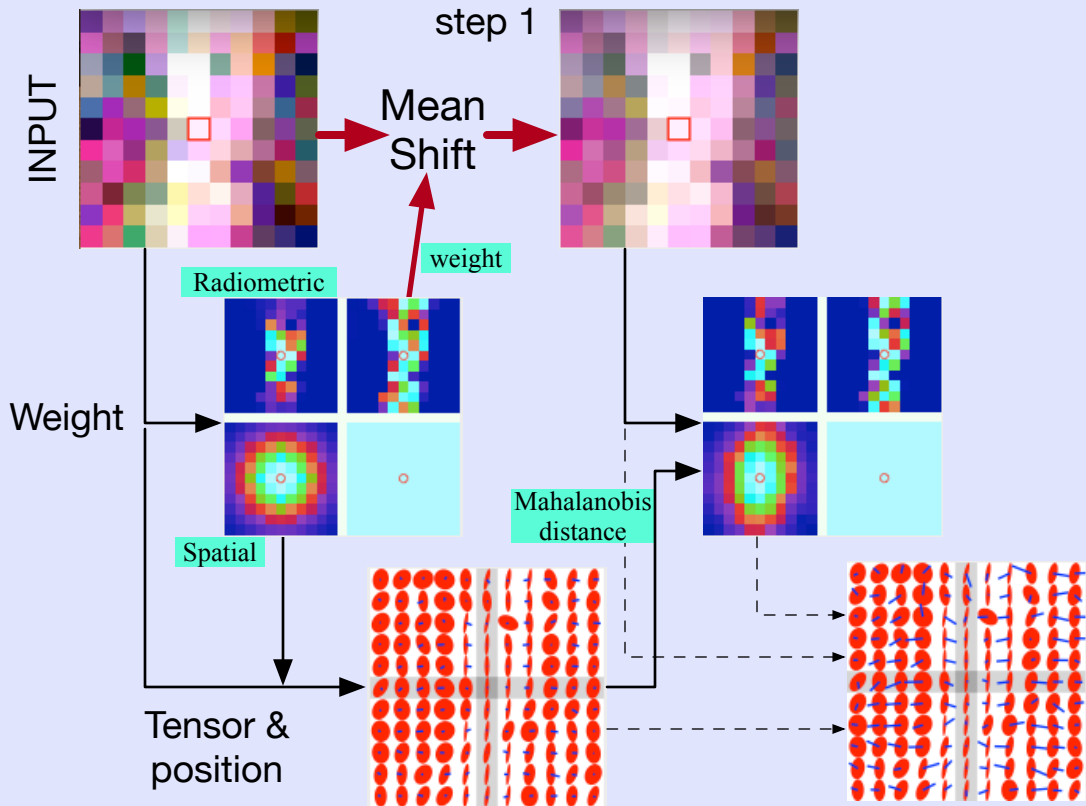
$$F_{\text{hift}} V = \alpha \text{ value}_V + (1-\alpha) \text{ Mean}_V$$

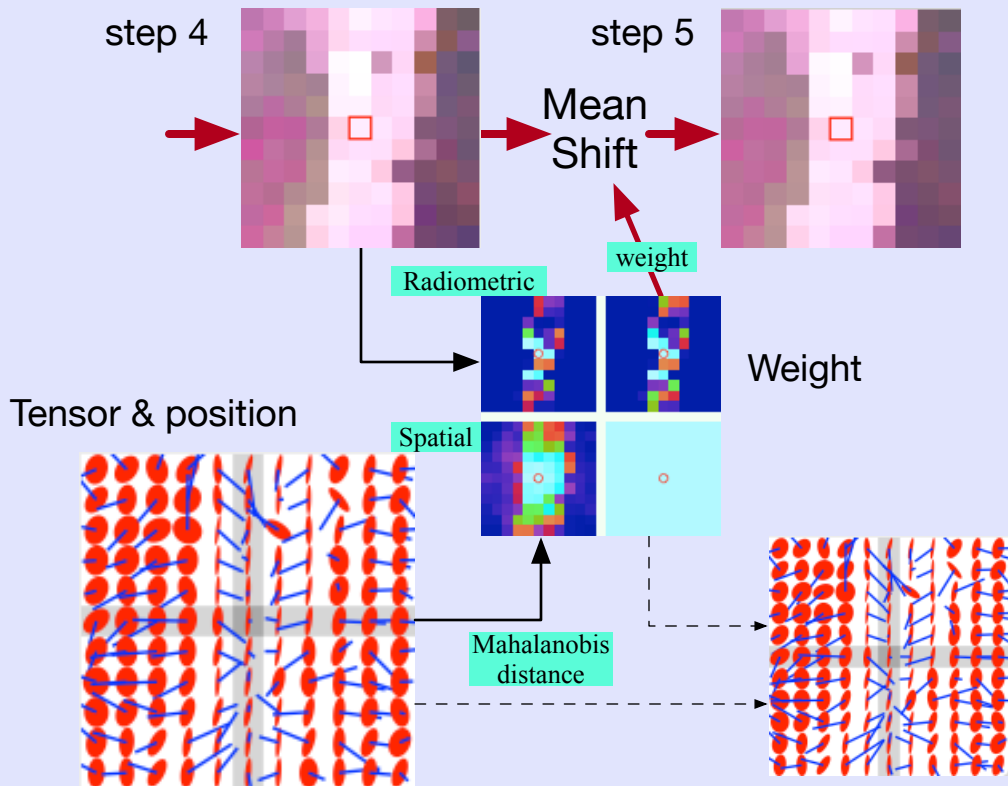
Tensor



- **Mahalanobis pixel distance**

Use V_i to calculate Mahalanobis pixel distances





Vertical Structure

input

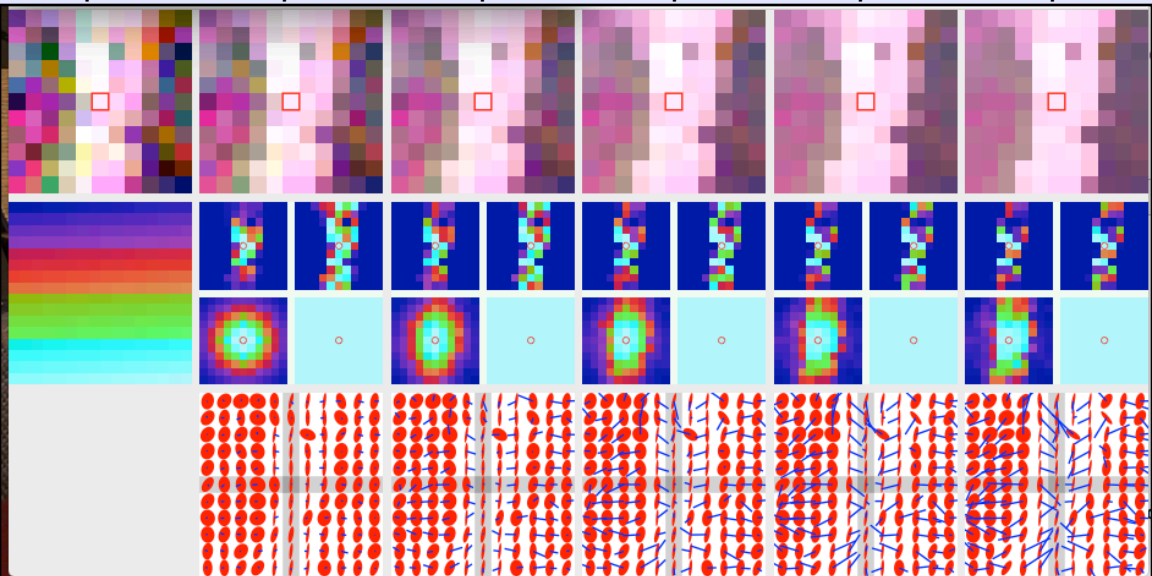
step 1

step 2

step 3

step 4

step 5



Uniform Field

input

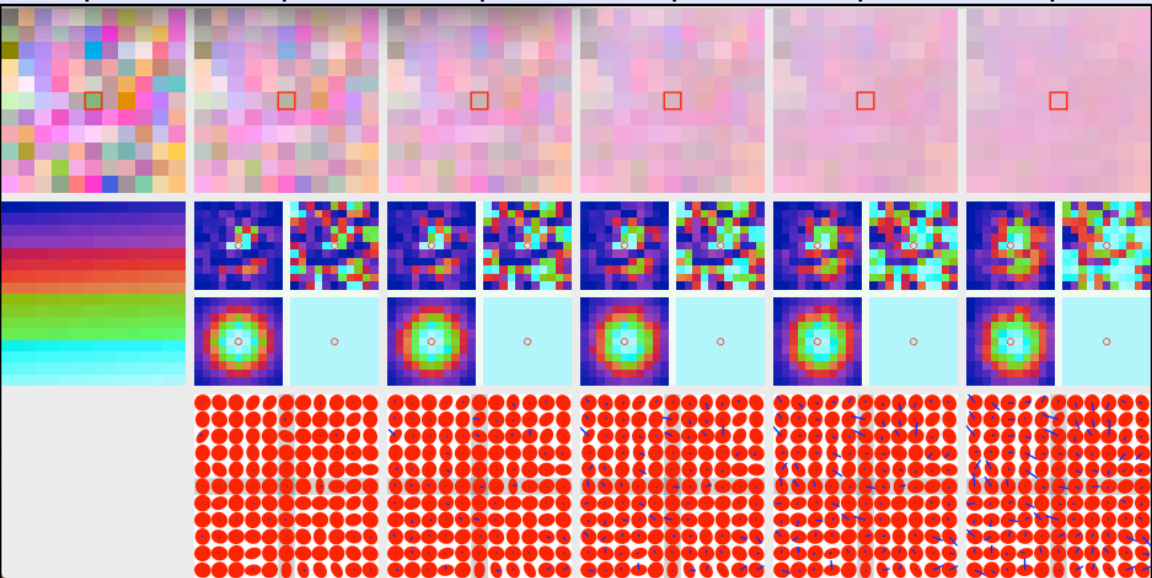
step 1

step 2

step 3

step 4

step 5



Low Contrast Edge

input

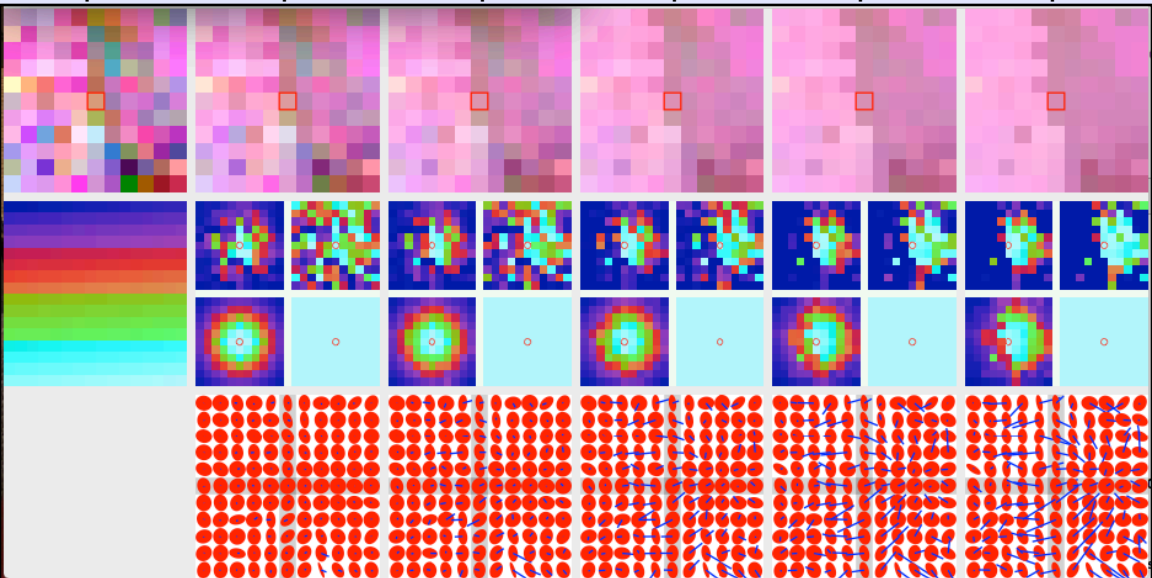
step 1

step 2

step 3

step 4

step 5



High Contrast Spot

input

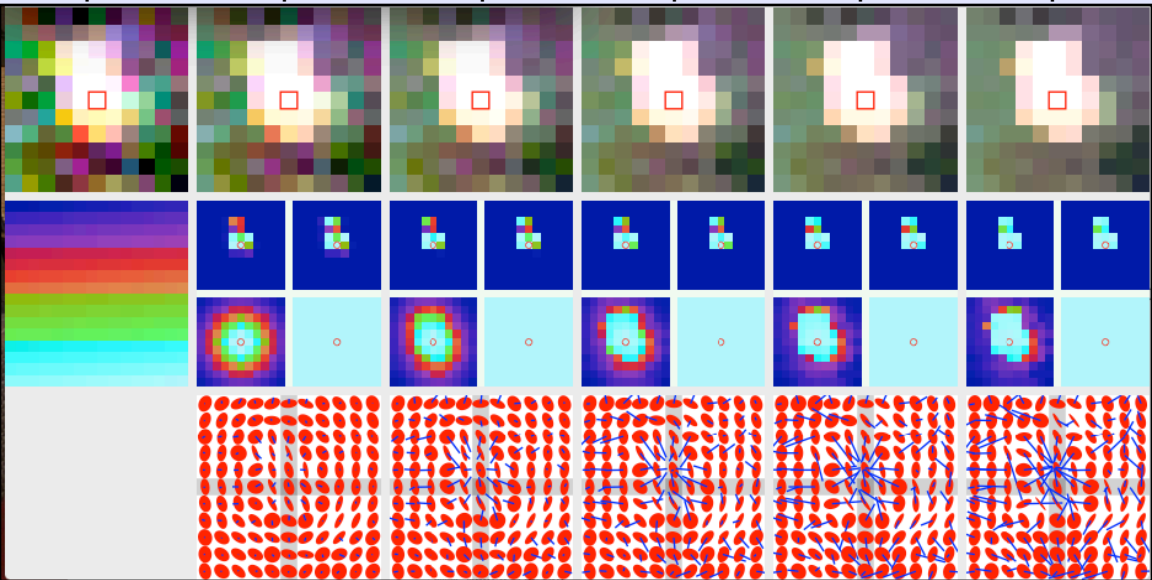
step 1

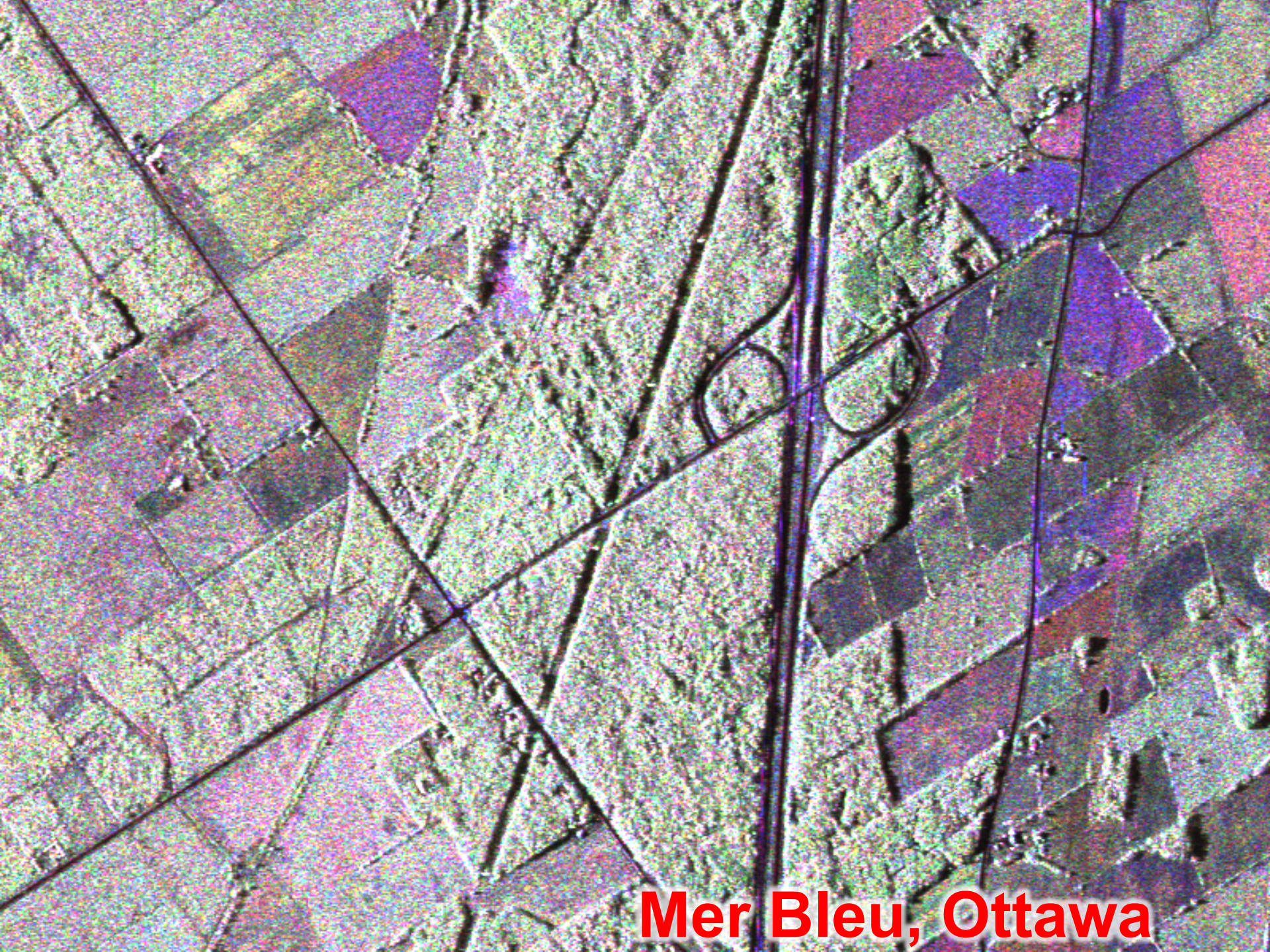
step 2

step 3

step 4

step 5





Mer Bleu, Ottawa



MeanShift

Oberfaffenhofen



MeanShift



original



meanshift



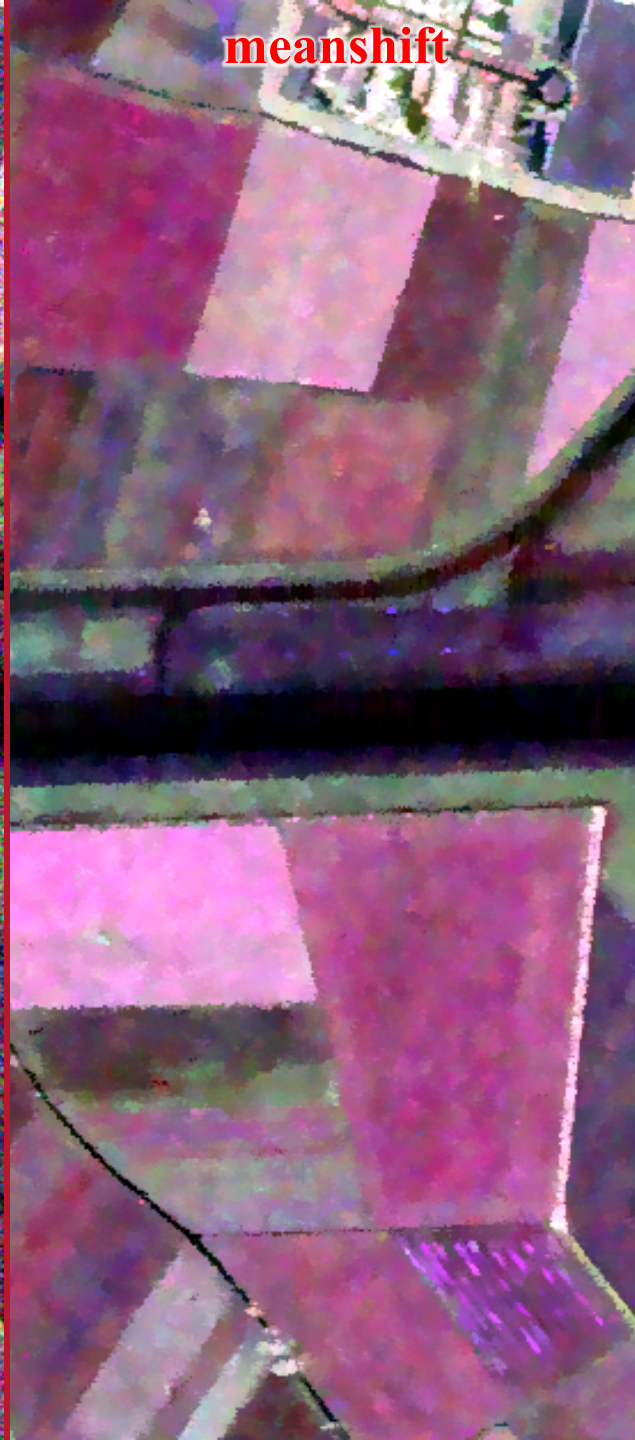
sigma



original



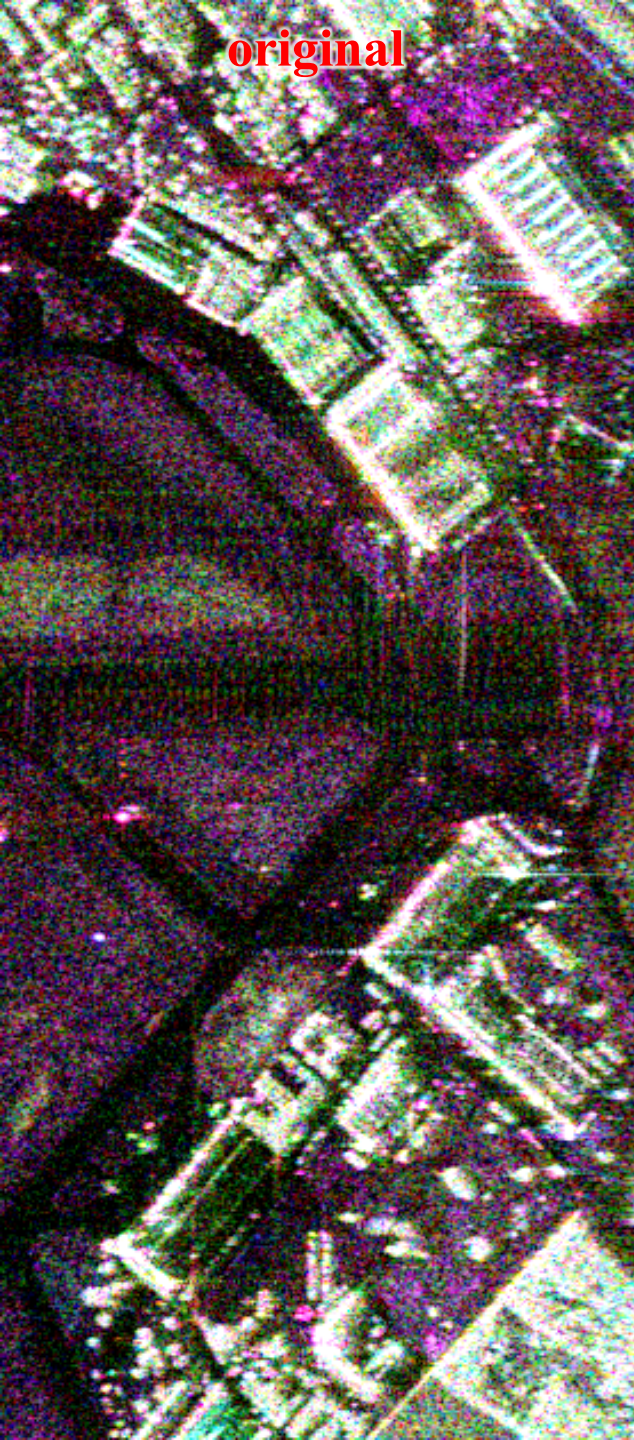
meanshift



sigma



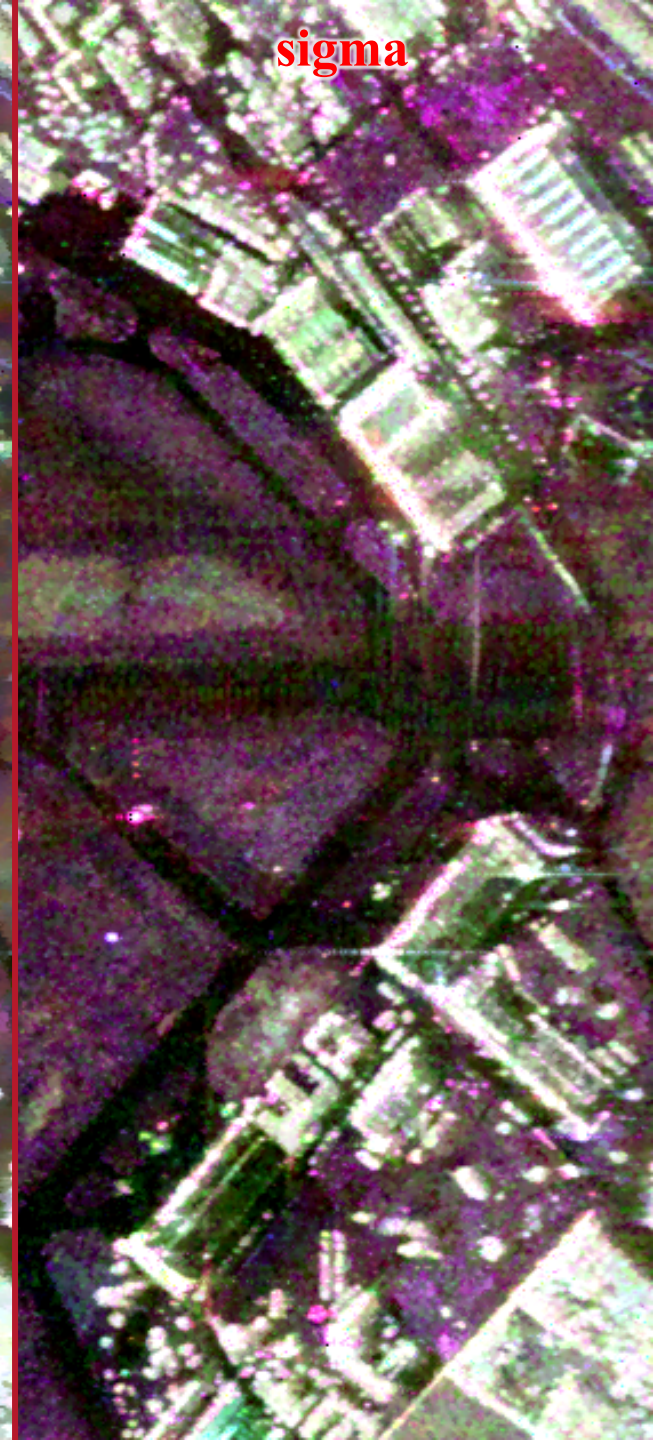
original



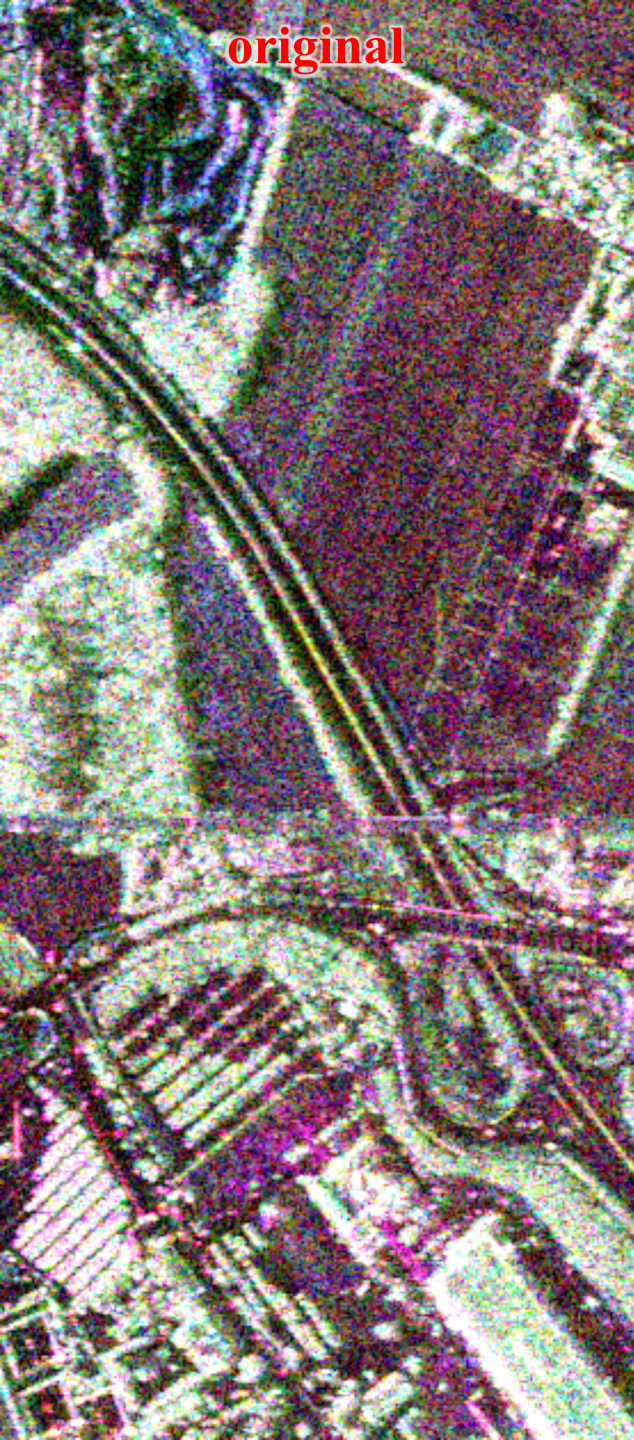
meanshift



sigma



original



meanshift



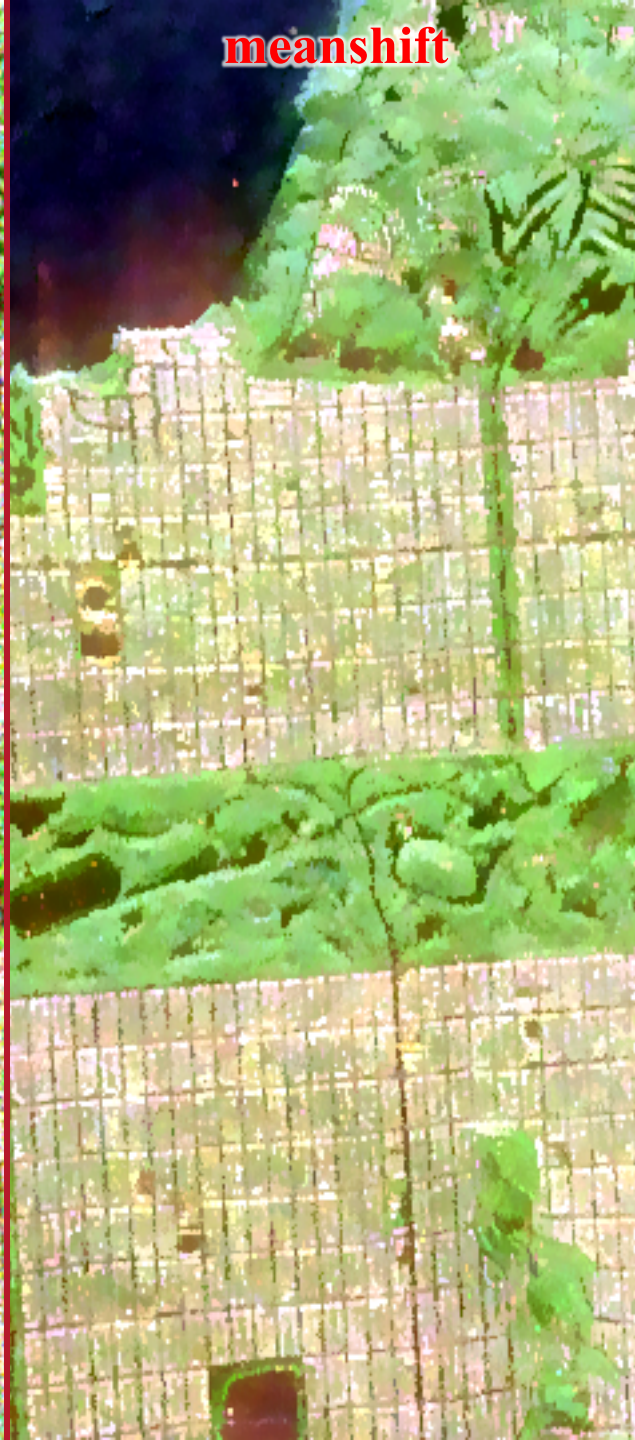
sigma



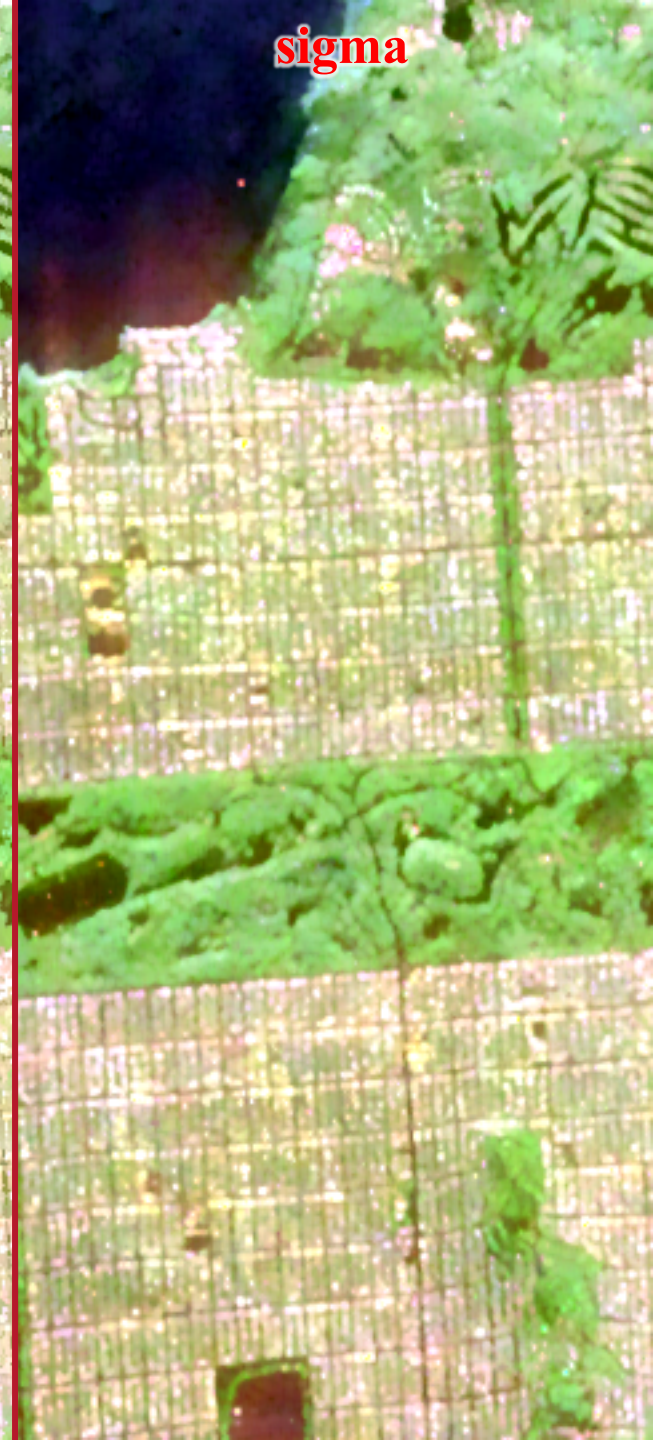
original



meanshift



sigma



CONCLUSION

- MeanShift can perform good image filtering.
- Position covariance tensor can provide a good textural attribute (ellipse orientation and elongation).
- Spatial attribute can be used in MeanShift to preserve edges.